

## Servo pillar CPSM



High load capability



High speed capability



Virtually maintenance free





## Customized solutions

Up to 65% weight saving

Up to 100mm/s high speed  
pillars

# Servo pillar CPSM



## Features

- High dynamic servo or brushless DC motor for high speed up to 100 mm/s
- High performance ball screw for high load capacity up to 5 kN
- Extruded aluminum profiles for a very robust design
- Manually adjusted gliders for very high stiffness and high eccentric loads
- Encoder system of the motor and high quality gearbox enable high positioning accuracy and high repeatability (0,1 mm)

## Benefits

- High nominal power of the motor allows for high duty cycle of the pillar
- Customized motor adapter for highest flexibility (max. motor diameter 90 mm)
- Customized top and bottom plate to fit most of the applications
- Customized aluminum profile colour (anodized) to fit application design needs
- Optional brake to release the motor when it's in position and to increase the duty cycle
- Preloaded bearing arrangement also for ceiling mount applications (only available without damping system)

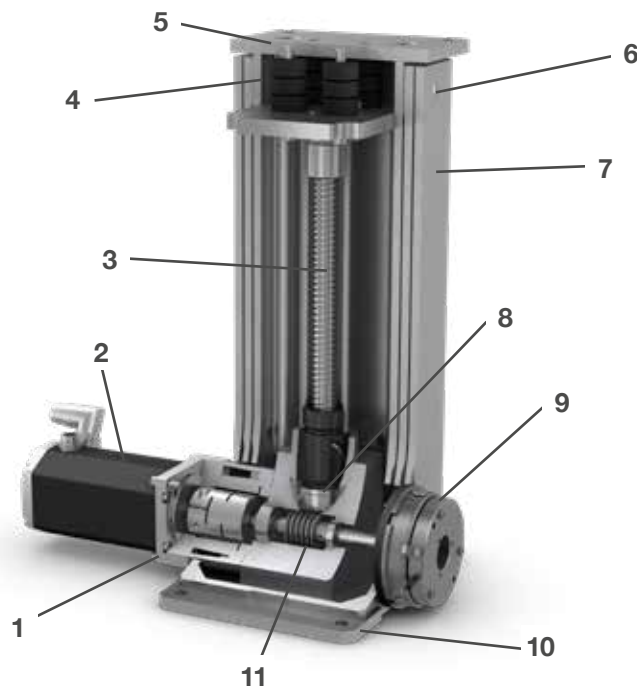
## Product description

Telescopic pillars CPSM are the ideal solution to combine strong guiding functions with linear movements.

The robust, manually adjusted and virtually backlash-free aluminum extrusions are able to carry high excentric loads in push and pull directions.

To provide enough power to lift and lower heavy weights with high speed, the pillars are equipped with brushless DC or servo motors. Of course, Ewellix also supports the usage of preferred motors with a customizable motor interface.

Optional brakes and damping elements are key features that allow an effective usage in heavy duty industrial applications.



1. Standard or customized motor interface
2. Motor (Brushless DC or servo AC)
3. High efficiency ball screw
4. Optional damping system
5. Customized top plate
6. Backlash-free long lasting guiding pads
7. 2 or 3 section extruded aluminum guiding tubes
8. Preloaded bearing arrangement
9. Optional electromechanical brake
10. Customized bottom plate
11. Low friction worm gear reduction

# CPSM

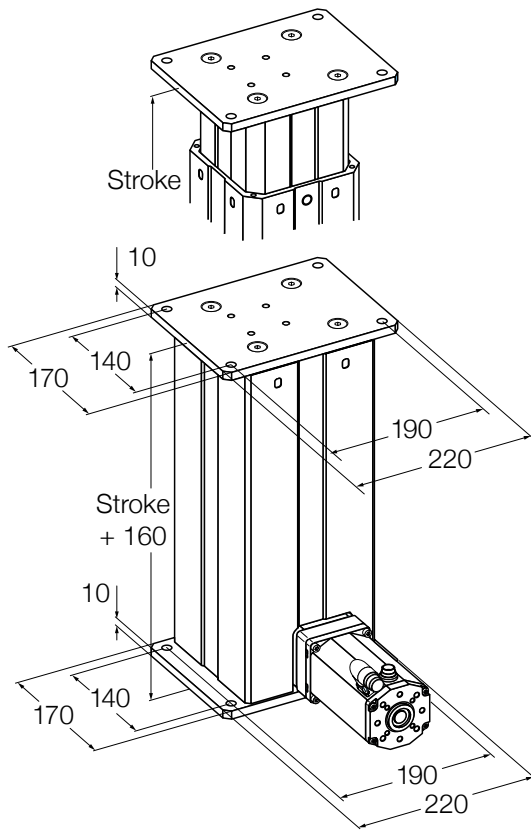
## Servo pillar



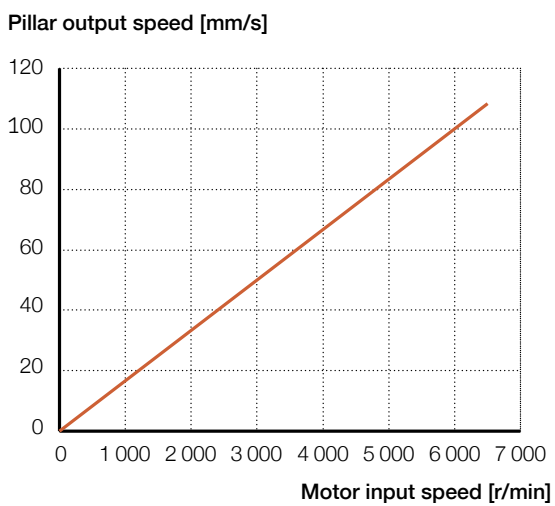
### Technical data

Designation	Symbol	Unit	w/o motor	BG75	1FK7034
<b>Performance Data</b>					
Continuous force @ zero speed	$F_{c0}$	kN	5	4,013	5
Continuous force @ max. speed	$F_c$	kN	5	4,013	4,013
Peak force @ zero speed	$F_{p0}$	kN	5	5	5
Peak force @ max. speed	$F_p$	kN	5	5	5
Dynamic load capacity	C	kN	21	21	21
Holding force (motorbrake option)	$F_{\text{Hold-MB}}$	kN	N/A	5	5
Holding force (external brake option)	$F_{\text{Hold-EB}}$	kN	5	5	5
Max. linear speed	$v_{\text{max}}$	mm/s	–	62	100
Max. acceleration	$a_{\text{max}}$	m/s <sup>2</sup>	6	6	6
Duty cycle	D	%	100	100	100
<b>Mechanical Data</b>					
Screw type	–	–	Ball screw	Ball screw	Ball screw
Screw diameter	$d_{\text{screw}}$	mm	20	20	20
Screw lead	$p_{\text{screw}}$	mm	10	10	10
Lead accuracy	–	–	G7	G7	G7
Stroke <sup>1)</sup>	s	mm	100...700	100...700	100...700
Internal overstroke each side	$s_0$	mm	1	1	1
Backlash	$s_{\text{backlash}}$	mm	0,07	0,07	0,07
Gear reduction	i	–	10	10	10
Efficiency	$\eta$	%	58	52	51
<b>Electrical Data</b>					
Motor type	–	–	N/A	Brushless DC	Servo
Nominal voltage	U	V DC	N/A	40	N/A
Nominal current	I	A	N/A	12,7	1,3
Peak current	$I_{\text{peak}}$	A	N/A	10,8	1,9
Nominal power	P	kW	N/A	0,45	0,6
<b>Environment</b>					
Ambient temperature	$T_{\text{ambient}}$	°C	0...+50	0...+50	0...+50
Max. humidity	$\phi$	%	95	95	95

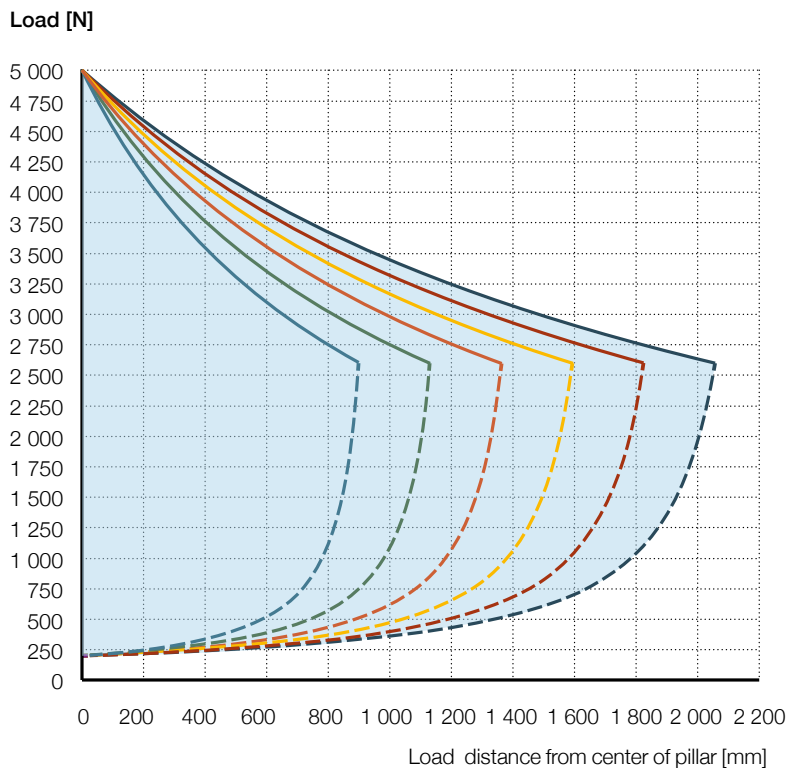
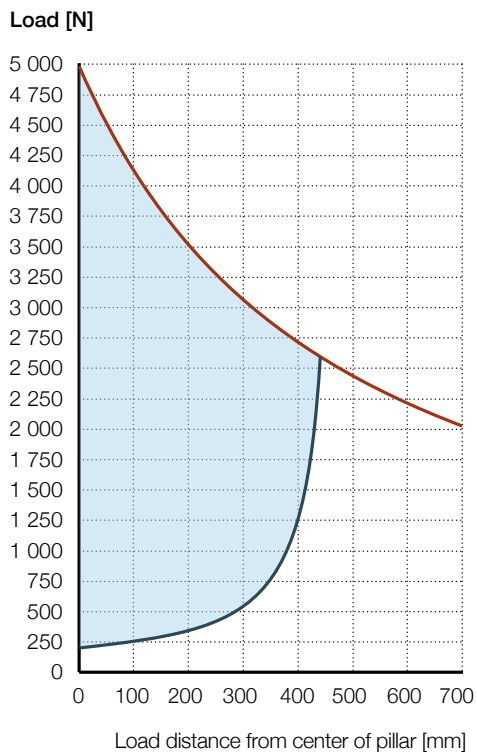
### Dimensional drawing



### Performance diagram



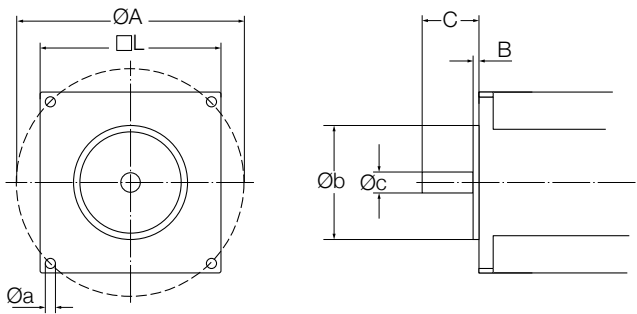
### Performance diagrams



- |                                 |                                 |                                 |
|---------------------------------|---------------------------------|---------------------------------|
| — Over load limit stroke 200    | — Over load limit stroke 400    | — Over load limit stroke 600    |
| - - Under load limit stroke 200 | - - Under load limit stroke 400 | - - Under load limit stroke 600 |
| — Over load limit stroke 300    | — Over load limit stroke 500    | — Over load limit stroke 700    |
| - - Under load limit stroke 300 | - - Under load limit stroke 500 | - - Under load limit stroke 700 |

## Adapter for third-party motors

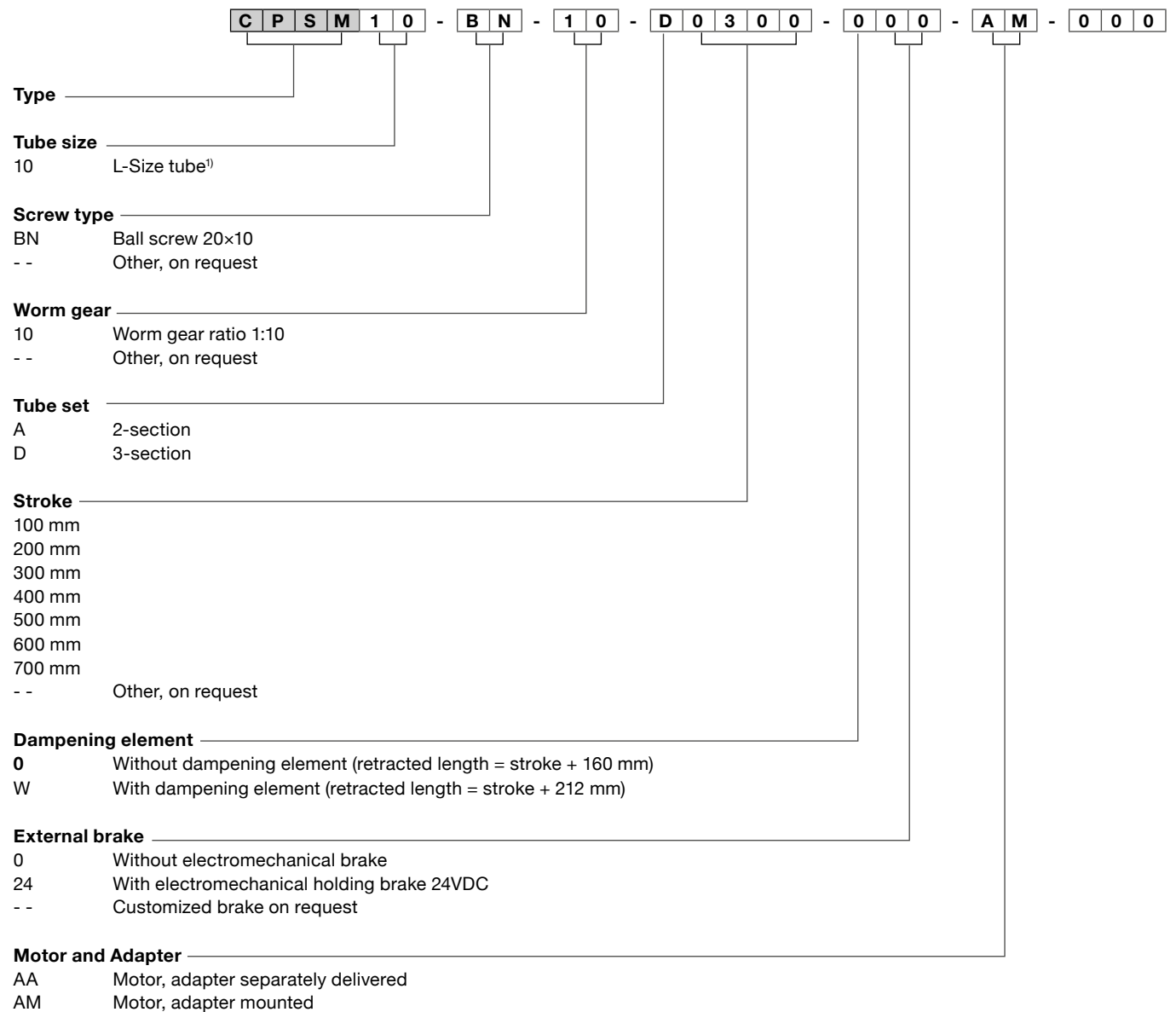
In order to attach your preferred motor to the pillar, SKF offers tailor-made solutions within the specifications below. For motor specifications which are not covered by those below, please contact SKF.



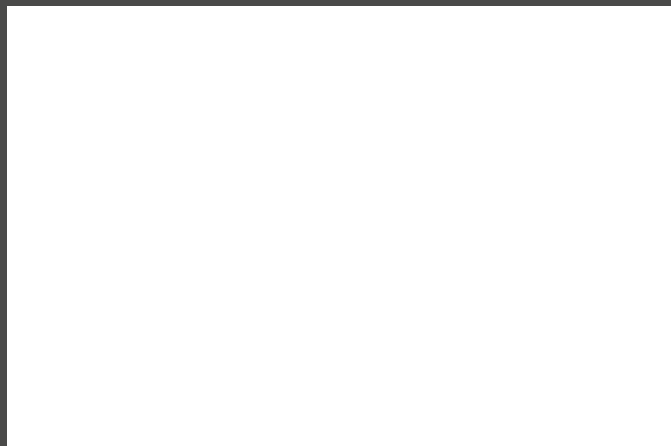
Designation	Symbol	Unit	Min.	Max.
Motor housing	□ L	mm	60	95
Motor centering	Øb	mm	4/	95
Centering height	B	mm	1	5
Fixing diameter	ØA	mm	52	103
Shaft diameter	Øc	mm	11	19
Shaft length	C	mm	15	48

# Ordering key

## Linear units



<sup>1)</sup> 3- sections: □ 163 mm / 2-sections: □ 146 m



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